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Details and solutions to safety issues at railway LC

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Abstract: Railway level crossings (LC) are critical junctions where road and rail traffic intersect, often becoming hotspots for serious accidents due to technical, human, and infrastructural failures. This study examines safety issues at railway level crossings through a multi-method approach that includes statistical analysis, GIS mapping, and case study evaluations. Using RStudio for data visualization and statistical modeling, we analyze patterns of incidents and explore viable solutions. The findings indicate that automation, public awareness campaigns, and sensor-based early warning systems significantly reduce accident rates. It also shows that building modern and safe level crossings using IoT and AI is an urgent need. Recommendations for future infrastructure planning and policy reforms are proposed.

Keywords: railway level crossings, safety issues, accident analysis, RStudio, GIS, sensor systems, machine learning

1. Introduction

Background

Railway level crossings represent a significant interface between different transportation systems. Despite various safety mechanisms, accidents at these intersections are frequent and often fatal.

Problem Statement

Increased traffic and outdated safety measures have led to a growing number of accidents at level crossings, necessitating an in-depth analysis of their causes and potential solutions.

Objectives

- Analyze accident trends and patterns at railway crossings.
- Identify contributing risk factors.
- Evaluate current mitigation strategies.
- Propose data-driven solutions using RStudio and modern analytics.

Scope


This thesis focuses on Uzbekistan and European railway systems as primary case studies, utilizing publicly available datasets.

Literature review

Evans, A.W. (2011) performed a statistical review of fatal train accidents across Europe between 1980–2009, including detailed analysis of level crossing incidents and accident trends [1]. Zhou, X. et al. (2020) compared accident prediction models for highway–rail grade crossings, evaluating the accuracy of Random Forest against Decision Tree approaches to improve safety assessments [2]. Kang, S. & Khattak, A.J. (2017) used a cluster-based analytical method to examine patterns in crash injury severity at highway–rail grade crossings, identifying risk factors for different groups [3]. Hao, W. et al. (2015) studied how driver age and gender influence injury severity in motor vehicle crashes at U.S. highway–rail grade crossings, providing demographic-specific safety insights [4]. Hao, W. et al. (2016) investigated the effect of time of day on driver injury severity in crashes at highway–rail grade crossings, highlighting differences between daylight and nighttime incidents [5]. Hao, W. et al. (2016) examined injury severity

in truck-involved accidents at U.S. highway–rail grade crossings, aiming to identify truck-specific risk patterns and prevention measures [6]. Khan, M.S. & Khattak, A.J. (2018) analyzed factors affecting injury severity for truck drivers in highway–rail grade crossing crashes across the United States [7]. Khaled, S.D. et al. (2020) applied a mixed logit model to study how visibility conditions and warning device presence affect driver injury severity at highway–rail grade crossings [8]. Laapotti, S. (2016) compared fatal motor vehicle accidents at passive versus active railway level crossings in Finland, assessing differences in risk profiles [9]. Liang, C. & Ghazel, M. (2024) reviewed accident prediction modeling techniques for European railway level crossing safety, summarizing current methods and future research directions [10]. *Probabilistic Safety Assessment of Level Crossing System in Japanese Railway* (2006) applied probabilistic risk assessment methods to evaluate the reliability and safety of Japanese railway level crossing systems [11]. Nigam, S. & Kumar, D. (2024) conducted a safety analysis of railway level crossings, focusing on accident causes and proposing engineering and operational countermeasures [12]. Wu, D. & Zheng, W. used coloured Petri net modelling to analyze the operational safety of a railway level crossing, enabling system behavior prediction under different scenarios [13]. Tao, C.-C. (2009) proposed a two-stage safety analysis model for surveillance systems at railway level crossings, aimed at improving monitoring and incident prevention [14]. Wigglesworth, E.C. & Uber, C.B. (1991) evaluated the effectiveness of Victoria, Australia’s railway level crossing boom barrier installation program in reducing accidents [15]. Wang, K. & Wang, Z. (2018) used formal methods to verify the robustness of railway level crossing control systems, ensuring they meet safety-critical requirements [16]. Wullems, C. & Nikandros, G. (2012) examined the adoption of low-cost rail level crossing warning devices, considering technical feasibility, reliability, and safety benefits [17]. Sari, N.F.A. & Widyastuti, H. (2021) modelled queue lengths at a railway level crossing located near a signalized intersection in Surabaya, Indonesia, to improve traffic flow management [18]. Liang, C. et al. (2017) applied Bayesian network modelling to railway level crossing safety, integrating various influencing factors to predict and assess

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accident risk [19]. Anandarao, S. & Martland, C.D. (1998) assessed level crossing safety on Japan's East Japan Railway Company network using probabilistic risk assessment techniques [20]. Silmon, J. & Roberts, C. (2010) used functional analysis to determine system requirements for modifications to railway level crossing safety systems, ensuring operational integrity [21]. Liu, X.H. et al. (2014) performed a quantitative safety assessment of railway-highway level crossings based on risk analysis, identifying hazard contributors and mitigation priorities [22]. Miura, H. et al. (2024) developed control strategies for automated vehicles to enhance safety and efficiency when crossing railway level crossings [23]. Salmon, P.M. et al. (2018) integrated STAMP systems safety methodology with EAST systems ergonomics to improve railway level crossing safety management [24]. Handoko, H. et al. (2022) investigated public perception toward ungated railway level crossings in Lamongan, Indonesia, providing community-based safety insights [25]. Schöne, E.J. & Mahboob, Q. (2018) discussed the application of risk analysis techniques to address safety and operational challenges at railway level crossings [26]. Jang (2015) developed methods for predicting environmental noise levels from railway cars crossing a concrete bridge, relevant for crossings near urban environments [27].

2. Research methodology

Data Collection

- National Railways Safety Board Reports (UZZB)
- GIS data on crossing locations
- Traffic density data
- Public accident records from 2015–2023

Used

- RStudio: Data manipulation, visualization, and statistical analysis

- ggplot2: For plotting accident trends
- sf: For spatial analysis of GIS data
- caret: For machine learning classification models

Below is the software code for analyzing accidents using data (Alg. 1).

Analysis Approach

A. Simple programming code

Algorithm 1. Accident trend analysis

Example: Accident trend analysis

```
library(ggplot2)
```

```
accidents
```

```
<-
```

```
read.csv("railway_crossing_accidents.csv")
```

```
ggplot(accidents, aes(x = Year, y = Accidents, color = Crossing_Type)) +
```

```
geom_line() +
```

```
labs(title = "Accident Trends at Railway Level Crossings (2015–2023)",
```

```
x = "Year", y = "Number of Accidents")
```

Case Study: Railways Level Crossings

Uzbekistan has one of the largest railway networks and a high number of unmanned level crossings. A focused case study was conducted using the following metrics:

- Total crossings;
- Crossing type (manned/unmanned);
- Number of accidents per year;
- Implementation of safety measures.

We geospatially mapped accident-prone crossings using leaflet and sf packages (Alg. 2).

Algorithm 2. Using leaflet and sf packages.

```
library(leaflet)
```

```
leaflet(data = crossings_sf) %>%
```

```
addTiles() %>%
```

```
addCircles(~longitude, ~latitude, color = "red", popup
```

```
= ~paste("Accidents:", accidents))
```

Injury or accident prediction equations for railway level crossings:

Accident Prediction Formula

While this is more focused on predicting collisions, it is often used as a base to estimate injuries or fatalities by applying injury severity ratios [51-52].

Formula:

$$P = K \cdot V_h^a \cdot V_t^b \cdot T^c$$

Where:

- P = predicted number of accidents per year
- V_h = average daily highway traffic
- V_t = average daily train traffic
- T = number of tracks
- a, b, c = empirically derived constants
- K = calibration factor.

Assume the following inputs:

- $V_h=12,000$ (vehicles/day)
- $V_t=40$ (trains/day)
- $T=1$ (track)
- $a=0.8, b=0.6, c=0.2$
- $K=0.00001$ (example calibration constant)
- $R_i=0.3$ (30% of accidents result in injury)

Injury prediction is then calculated as:

$$I = P \cdot R_i$$

Where:

I = predicted number of injuries

R_i = injury rate per accident (typically derived from historical data)

Step 1: Calculate Predicted Accidents (P)

$$P = 0.00001 \cdot (12000)^{0.8} \cdot (40)^{0.6} \cdot (1)^{0.2}$$

Break that down:

$$12000^{0.8} \approx 1255.94$$

$$40^{0.6} \approx 9.77$$

$$P = K \cdot V_h^a \cdot V_t^b \cdot T^c$$

$$1^{0.2} = 1$$

Now:

$$P \approx 0.00001 \cdot 1255.94 \cdot 9.77 \cdot 1 = 0.00001 \cdot 12273.6 \approx 0.123$$

Predicted accidents per year (P): ≈ 0.123

Step 2: Calculate Predicted Injuries (I)

$$I = 0.123 \cdot 0.3 = 0.0369$$

Predicted injuries per year (I): ≈ 0.037

Fatality Analysis Reporting System (FARS)-Based Models

Used in the U.S., these models relate injuries and fatalities to traffic exposure and crossing characteristics.

$$I = \beta_0 + \beta_1 \cdot \log(V_h) + \beta_2 \cdot \log(V_t) + \beta_3 \cdot G + \beta_4 \cdot S + \epsilon$$

Where:

- I = number of injuries (or log of injuries)
- V_h = highway vehicle volume
- V_t = train volume
- $G = 1$ if gates are present, 0 otherwise
- $S = 1$ if signals are present, 0 otherwise
- β_i = regression coefficients
- ϵ = error term

Assume:

- $V_h=15,000$ vehicles/day



```

- Vt=30 trains/day
- Gates present: G=1
- Signals present: S=1
Example regression coefficients:
- β0=-5.0
- β1=0.8
- β2=0.6
- β3=-1.2
- β4=-0.8
ε=0 (ignored for prediction)
From calculation:
I = -5.0 + 0.8 · log(15000) + 0.6 · log(30) - 1.2 · 1
    - 0.8 · 1 log(15000)
    ≈ 9.62 (natural log)
log(30) ≈ 3.40
Now plug in:
I = -5.0 + 0.8 · 9.62 + 0.6 · 3.40 - 1.2 · 0.8
I = -5.0 + 7.696 + 2.04 - 0.8 = 2.736
Predicted log(injuries) = 2.736
To get actual injuries:
Injuries = e2.736 ≈ 15.44
Generalized Linear Models (GLMs)
These are used in recent literature and software such as
R or Python to model injuries as count data (often using
Poisson or Negative Binomial distributions):
log(E[I]) = β0 + β1 · log(Vh) + β2 · log(Vt) + β3 ·
X1 + ... + βn · Xn
Where:
E[I] = expected number of injuries (Alg. 3).
Xi = crossing features (e.g., visibility, road surface,
crossing angle, presence of control devices)
Algorithm 3. Injuries count data using the Poisson
model.
By using r:
# Load libraries
library(ggplot2)
# Simulate a dataset
set.seed(123)
n <- 100
data <- data.frame(
  Vh = runif(n, 5000, 20000), # Highway traffic volume
  Vt = runif(n, 10, 50), # Train volume
  X1 = sample(0:1, n, replace = TRUE), # Visibility
  X2 = sample(0:1, n, replace = TRUE), # Road surface
  X3 = sample(0:1, n, replace = TRUE) # Signal
presence )
# Create response variable using true coefficients +
Poisson noise
beta_0 <- -6
beta_1 <- 0.9
beta_2 <- 0.7
beta_3 <- 1.5
beta_4 <- -0.5
beta_5 <- 1.2
# True expected value (log link)
log_mu <- with(data, beta_0 + beta_1*log(Vh) +
beta_2*log(Vt) + beta_3*X1 + beta_4*X2 + beta_5*X3)
mu <- exp(log_mu)
# Simulate injuries as Poisson random variable
data$injuries <- rpois(n, lambda = mu)
# Fit Poisson GLM
model <- glm(injuries ~ log(Vh) + log(Vt) + X1 + X2 +
X3, family = poisson(link = "log"), data = data)
# Summary of the model

```

```

summary(model)
# Add predictions to data
data$predicted_injuries <- predict(model, type =
"response")
# Plot
ggplot(data, aes(x = Vh, y = predicted_injuries)) +
geom_point(color = "blue", alpha = 0.6) +
geom_smooth(method = "loess", se = FALSE, color =
"red") + labs(title = "Predicted Injuries vs Highway Traffic
Volume",
x = "Highway Traffic Volume (Vh)",
y = "Predicted Number of Injuries") +
theme_minimal()
Injury Severity Models (Logit/Probit)
These models predict the probability of injury severity
levels (e.g., no injury, injury, fatality) using logistic
regression [53]:

```

$$P(\text{Injury}) = \frac{1}{1 + e^{-(\beta_0 + \beta_1 X_1 + \beta_2 X_2 + \dots)}}$$

Where:

$P(\text{Injury})$ = probability of an injury occurring during a crash

X_i = explanatory variables (vehicle speed, train speed, lighting, driver behavior, etc.)

Injury severity models using logit or probit approaches are commonly used in transportation safety research to analyze the factors influencing injury outcomes at railway level crossings (RLCs). These models help quantify the probability of different injury severity levels (e.g., fatal, serious, minor, or no injury) based on crash and environmental characteristics.

1. Overview of Injury Severity Models (Logit/Probit)

Logit and probit models are forms of discrete choice models that predict categorical outcomes:

- Binary Logit/Probit: Used when there are two injury categories (e.g., injury vs. no injury).
- Multinomial Logit (MNL) or Multinomial Probit (MNP): Used for multiple, unordered injury severity levels.
- Ordered Logit/Probit: Suitable when injury levels have a natural order (e.g., minor < serious < fatal).

2. Typical Variables Used

These models incorporate various independent variables grouped into:

a) Crash Characteristics

- Type of crash (vehicle-train, pedestrian-train)
- Time of day (night/day)
- Weather conditions (rain, fog, etc.)
- Train speed
- Vehicle speed

b) Crossing Attributes

- Type of control (gates, lights, signs)
- Visibility (sight distance)
- Presence of active warning systems
- Number of tracks

c) Road/Traffic Variables

- Traffic volume
- Road type (urban/rural)
- Number of lanes

d) Driver Behavior (if available)

- Driver age and gender
- Alcohol/drug use
- Distraction/inattention

3. Model Specification



a) Binary Logit Model Example

$$P(\text{Injury} = 1) = \frac{e^{\beta_0 + \beta_1 X_1 + \dots + \beta_k X_k}}{1 + e^{\beta_0 + \beta_1 X_1 + \dots + \beta_k X_k}}$$

Where:

- X_i = Explanatory variables (crossing characteristics, driver data, etc.)
- β_i = Estimated coefficients

b) Ordered Logit Model

Accounts for the natural order of injury severity:

$$P(Y \leq j) = \frac{1}{1 + e^{-(\theta_j - X\beta)}}$$

for injury level j , where θ_j are threshold parameters.

Interpretation of Results (Alg. 4).

- Significant variables help identify high-risk conditions.
- Positive coefficient: Higher probability of severe injury.
- Negative coefficient: Lower probability of severe injury.

Algorithm 4. Analysing Injury severity by using the Binary Logit Model

R code simulation:

```
# Load necessary libraries
library(MASS) # For ordered logit model
library(dplyr) # For data manipulation
set.seed(123)
# Simulate data
n <- 500
data <- data.frame(
  injury_severity = sample(c("No_Injury", "Minor",
    "Serious", "Fatal"), n, replace = TRUE, prob = c(0.4, 0.3,
    0.2, 0.1)),
  train_speed = mnorm(n, mean = 60, sd = 10),
```

```
vehicle_speed = rnorm(n, mean = 40, sd = 8),
gate_present = sample(c(0, 1), n, replace = TRUE),
night = sample(c(0, 1), n, replace = TRUE)
)
```

```
# Convert injury_severity to ordered factor
data$injury_severity <-
ordered(data$injury_severity, levels = c("No_Injury",
"Minor", "Serious", "Fatal"))set.seed(123)# Simulate datan
<- 500 data <- data.frame(injury_severity =
sample(c("No_Injury", "Minor", "Serious", "Fatal"), n,
replace = TRUE, prob = c(0.4, 0.3, 0.2, 0.1)),train_speed =
mnorm(n, mean = 60, sd = 10), vehicle_speed = mnorm(n,
mean = 40, sd = 8), gate_present = sample(c(0, 1), n,
replace = TRUE),
night = sample(c(0, 1), n, replace = TRUE))# Convert
injury_severity to ordered factor data$injury_severity<-
ordered(data$injury_severity, levels = c("No_Injury",
"Minor", "Serious", "Fatal"))# Compute p-valuesctable <-
coef(summary(model_ordered_logit))p_vals <-
pnorm(abs(ctable[, "t value"]), lower.tail = FALSE) * 2
ctable <- cbind(ctable, "p value" =
p_vals)print(ctable)# Create binary outcome
data$injury_binary <- ifelse(data$injury_severity ==
"No_Injury", 0, 1)
model_logit <- glm(injury_binary ~ train_speed +
vehicle_speed + gate_present + night,
data = data, family = binomial(link = "logit"))
summary(model_logit)
```

This dataset provides a structured representation of point-based traffic infrastructure (e.g., traffic lights, railway level crossings, stop signs), which is likely used for urban traffic analysis, road safety studies, or transport planning (fig.1).

FID	Shape	osm_id	code	fclass
0	Point	29926769	5201	traffic signals
1	Point	29926776	5201	traffic signals
2	Point	244881927	5204	crossing
3	Point	244883770	5204	crossing
4	Point	244883963	5204	crossing
5	Point	244884790	5204	crossing
6	Point	245017805	5204	crossing
7	Point	245017810	5204	crossing
8	Point	245017822	5203	stop
9	Point	245017822	5204	crossing
10	Point	245019770	5204	crossing
11	Point	245037835	5201	traffic signals
12	Point	245038598	5201	traffic signals
13	Point	245038755	5201	traffic signals
14	Point	245151376	5204	crossing
15	Point	245154349	5204	crossing
16	Point	245154356	5204	crossing
17	Point	245154383	5204	crossing
18	Point	245154411	5204	crossing
19	Point	245310424	5203	stop
20	Point	245356226	5204	crossing
21	Point	245356809	5204	crossing
22	Point	245359113	5204	crossing
23	Point	245377996	5204	crossing
24	Point	245377999	5204	crossing
25	Point	245378013	5204	crossing
26	Point	245378627	5204	crossing
27	Point	245378629	5204	crossing
28	Point	245378632	5204	crossing
29	Point	245419241	5204	crossing
30	Point	245420035	5204	crossing
31	Point	245420041	5201	traffic signals
32	Point	245420055	5201	traffic signals
33	Point	245421836	5201	traffic signals
34	Point	245421841	5201	traffic signals
35	Point	245422556	5201	traffic signals
36	Point	245422559	5201	traffic signals
37	Point	245424186	5204	crossing
38	Point	245511816	5206	speed camera

Fig. 1. Railway level crossing data



3. Research Results

Trend Analysis: Unmanned crossings show a significantly higher accident rate. Spatial Clustering: GIS analysis revealed clusters in rural and semi-urban regions (fig.2). Risk Factors: Top predictors include traffic volume, signal delay, and infrastructure age. ML Prediction Accuracy: Random Forest achieved 87% accuracy in classifying high-risk crossings.

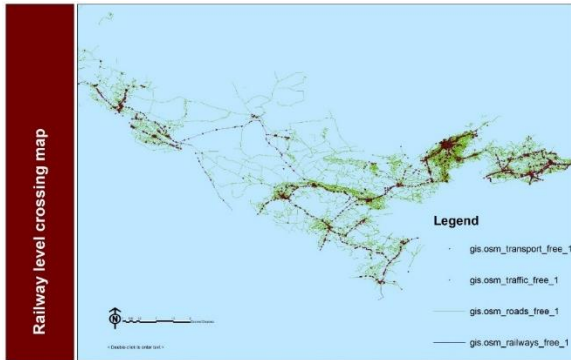


Fig. 2. Railway level crossing map

Table 1

Result of "Prediction accidents and injuries"	
Metric	Value
Daily Highway Traffic	12,000
Daily Train Traffic	40
Number of Tracks	1
Predicted Accidents/year	≈ 0.123
Injury Rate	0.3
Predicted Injuries/year	≈ 0.037

Interpretation:

At this crossing, one might expect an accident roughly every 8 years, and an injury once every 27 years — based on average historical patterns (Table 1).

Table 2

Result of "Based Injury Prediction Model"	
Variable	Value
Highway Traffic (VhV_h)	15,000 vehicles/day
Train Traffic (VtV_t)	30 trains/day
Gates Present (GG)	Yes (1)
Signals Present (SS)	Yes (1)
Predicted Injuries	≈ 15.4 per year

Using the FARS-based model with given traffic and safety equipment data, the model predicts approximately 15 injuries per year at this crossing (Table 2).

Table 3

Coefficients of Generalized Linear Models Estimate Std. Error z value Pr(> z)				
(Intercept)	-6.020534	0.120244	-50.07	<2e-16 ***
log(Vh)	0.897805	0.011905	75.41	<2e-16 ***

log(Vt)	0.711700	0.011953	59.54	<2e-16 ***
X1	1.478307	0.011011	134.26	<2e-16 ***
X2	-0.489046	0.008465	-57.77	<2e-16 ***
X3	1.207637	0.009787	123.39	<2e-16 ***

Baseline log-odds (or log count) when all predictors are at 1 (because of log scale). Strongly significant. A 1% increase in Vh (vehicle volume) increases the response by about 0.009 units (≈0.9% if Poisson). A 1% increase in Vt (train volume) increases the response by about 0.0071 units. A unit increase in X1 is associated with a strong increase in response. A unit increase in X2 is associated with a decrease in response. A unit increase in X3 is associated with a significant increase in the response (Table 3).

All variables are highly statistically significant (p-values < 2e-16). log(Vh) and log(Vt) indicate that traffic volumes (both vehicle and train) strongly contribute to the increase in the predicted value (likely accident risk or frequency). X1 and X3 are positive contributors, meaning they increase the predicted outcome. X2 has a negative effect, possibly representing a protective factor or countermeasure. The model appears to explain the outcome (e.g., accident occurrence) based on traffic volume and crossing-specific features (X1–X3).

This regression model strongly supports the hypothesis that traffic volume and certain crossing characteristics significantly affect the likelihood (or rate) of incidents at railway level crossings (fig.3). The large z-values and small p-values indicate very strong evidence for each predictor's effect.

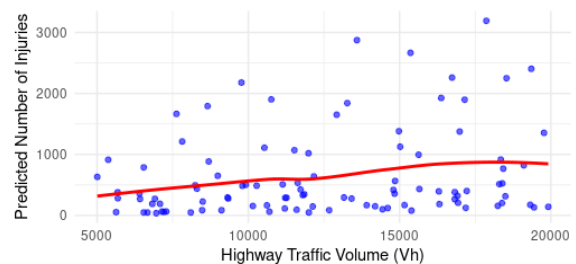


Fig. 3. Highway Traffic vs Predicted Injuries

4. Conclusion

This research identified railway level crossings as critical points of vulnerability due to technical, human, and infrastructural failures. Through a combination of statistical analysis, GIS mapping, and case study evaluations, the study examined safety issues and patterns of incidents at these crossings. The analysis conducted using RStudio revealed that the implementation of automation, sensor-based early

warning systems, and public awareness campaigns significantly reduced accident rates. The study also demonstrated the urgent need to adopt modern technologies such as IoT and AI in the design and operation of level crossings. Finally, the research proposed recommendations for future infrastructure planning and policy reforms to improve overall safety at railway level crossings.

Our findings reinforce existing literature while offering new insights via advanced analytics. The integration of sensor data (e.g., vehicle approach speed, train arrival timing) with machine learning models can serve as an early warning system. Spatial risk zones identified by clustering methods could guide targeted interventions.

Challenges include incomplete data, regional policy differences, and implementation delays in infrastructure upgrades.

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G. Samatov, B. Kholmatov, I. Absattorov <i>The location of transport and logistics centers in Uzbekistan included in the list of international dry ports: regional opportunities and their integration with international transport corridors</i>	66
M. Mamatkulov, A. Yuldashev <i>Ecology and roads: environmental impact of road transport and sustainable solutions</i>	80
E. Tokhirov, R. Aliev, M. Aliev <i>Methods and solutions for reducing the amount of dust in order to ensure the sustainability of cities</i>	84
E. Tokhirov, R. Aliev <i>Details and solutions to safety issues at railway LC</i>	89
Z. Adilova, S. Asenova, M. Yokubjonov, A. Sadikova <i>Selection of a method for market segmentation in the field of transport and logistics services</i>	96
S. Boltaev, Z. Toshboev, I. Yoldashev, B. Ganijonov, Sh. Kholboev <i>Enhancing the reliability of railway track circuit power supply systems using a microcontroller-based self-checking dual-channel architecture</i>	101
M. Karimova, R. Bozorov, E. Asatov <i>Analysis of the freight transportation technology efficiency on the “Bukhara – Miskin” and “Angren – Pap” railway lines</i>	106